

Differentiable Learning of Logical Rules for Knowledge Base Reasoning

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Joint work with Zhilin Yang and William W. Cohen

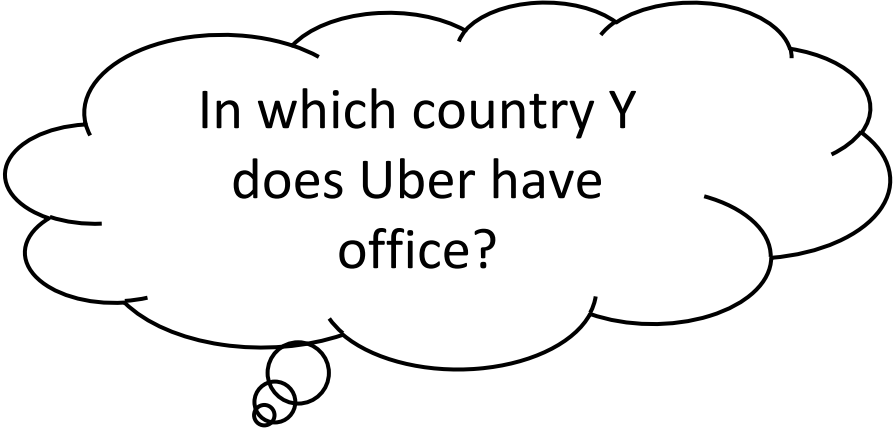


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Problem definition

- Knowledge base (KB) reasoning
 - KB: a set of binary relations between entities.
 - Reasoning: retrieve entities from KB based on queries.



In which country Y
does Uber have
office?



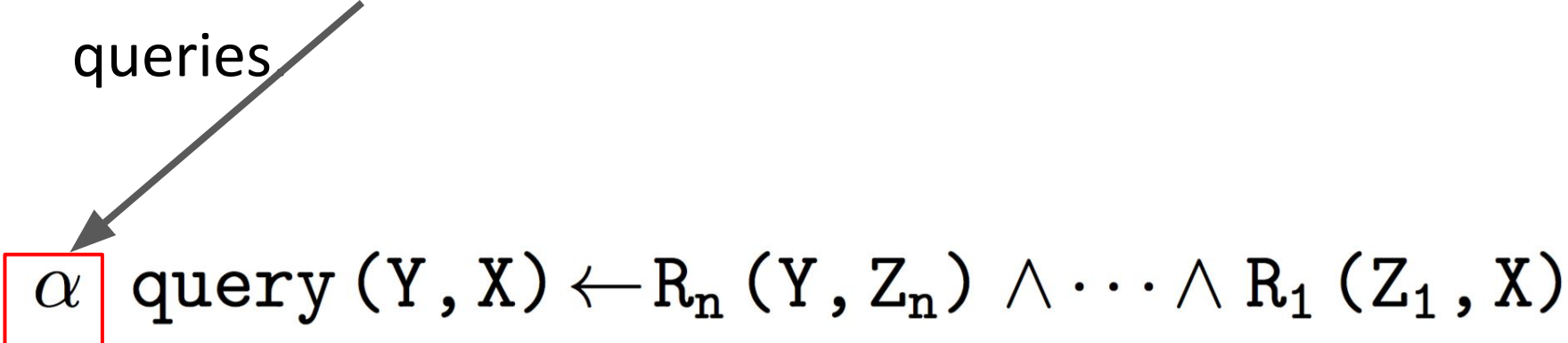
HasOfficeInCountry(Y, Lyft) ?



HasOfficeInCity(New York, Uber)
.....
HasOfficeInCity(Paris, Lyft)
CityInCountry(USA, New York)
.....
CityInCountry(France, Paris)

Our approach

- Learn **weighted chain-like logical rules** to answer queries


$$\alpha \text{ query } (Y, X) \leftarrow R_n (Y, Z_n) \wedge \cdots \wedge R_1 (Z_1, X)$$

0.7 HasOfficeInCountry (Y, X) \leftarrow CityInCountry(Y, W) \wedge HasOfficeInCity(W, X)

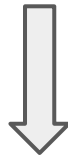
ungrounded variables



TensorLog Operators

- Represent **logical rule inference** using TensorLog operators (i.e. sparse matrices).
 - E = set of entities. R = set of binary relations.
 - For each entity i , define one-hot vector v_i .
 - For each relation R , define adjacency matrix M_R .

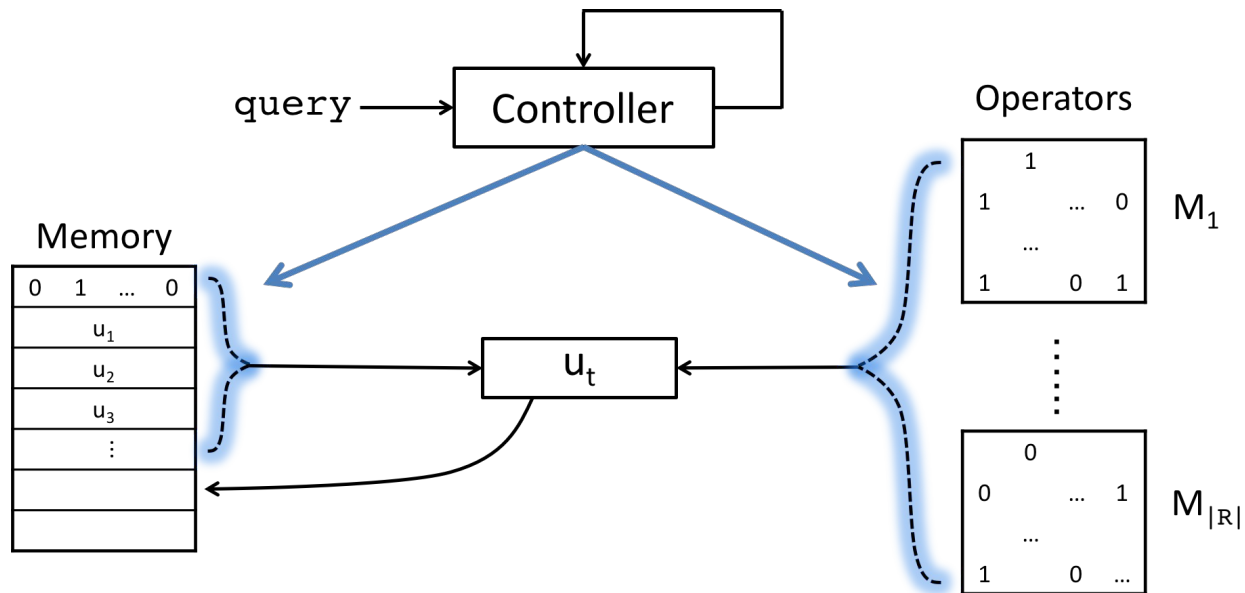
0.7 HasOfficeInCountry (Y, x) \leftarrow CityInCountry(Y, W) \wedge HasOfficeInCity(W, x)



$$v_y = 0.7 M_{\text{CityInCountry}} M_{\text{HasOfficeInCity}} v_x$$

Learn the logical rules

- Equivalent to **learning to compose** the operators.



$$\mathbf{u}_0 = \mathbf{v}_x$$

$$\mathbf{u}_t = \sum_{\mathbf{k}} a_t^{\mathbf{k}} \mathbf{M}_{\mathbf{R}_k} \left(\sum_{\tau=0}^{t-1} b_t^{\tau} \mathbf{u}_{\tau} \right) \quad \text{for } 1 \leq t \leq T$$

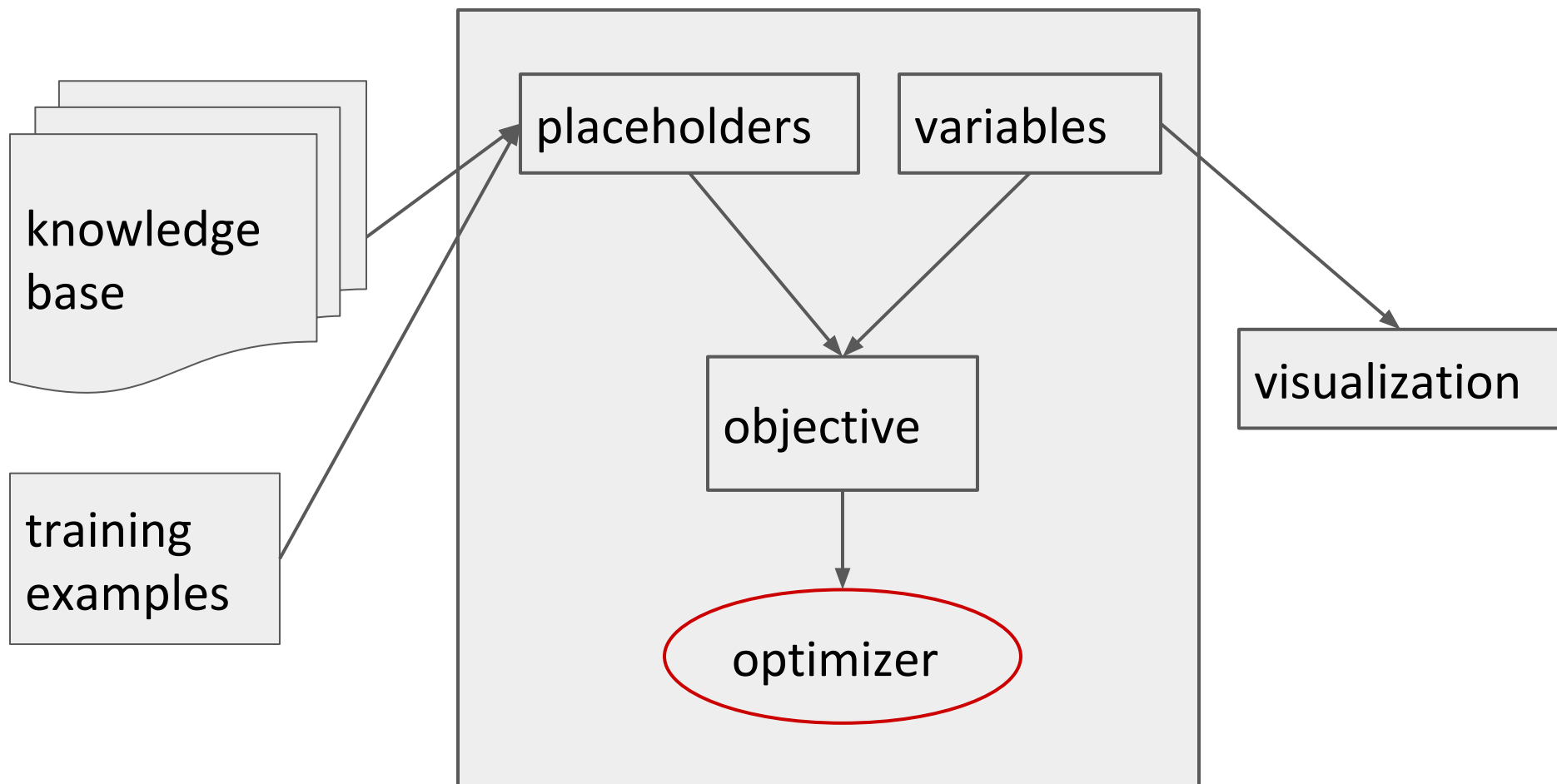
$$\mathbf{u}_{T+1} = \sum_{\tau=0}^T b_{T+1}^{\tau} \mathbf{u}_{\tau}$$

Implementation Outline

- Overview
- Learnable parameters
- Data flow and representation
- Training
- Sidelines for visualization

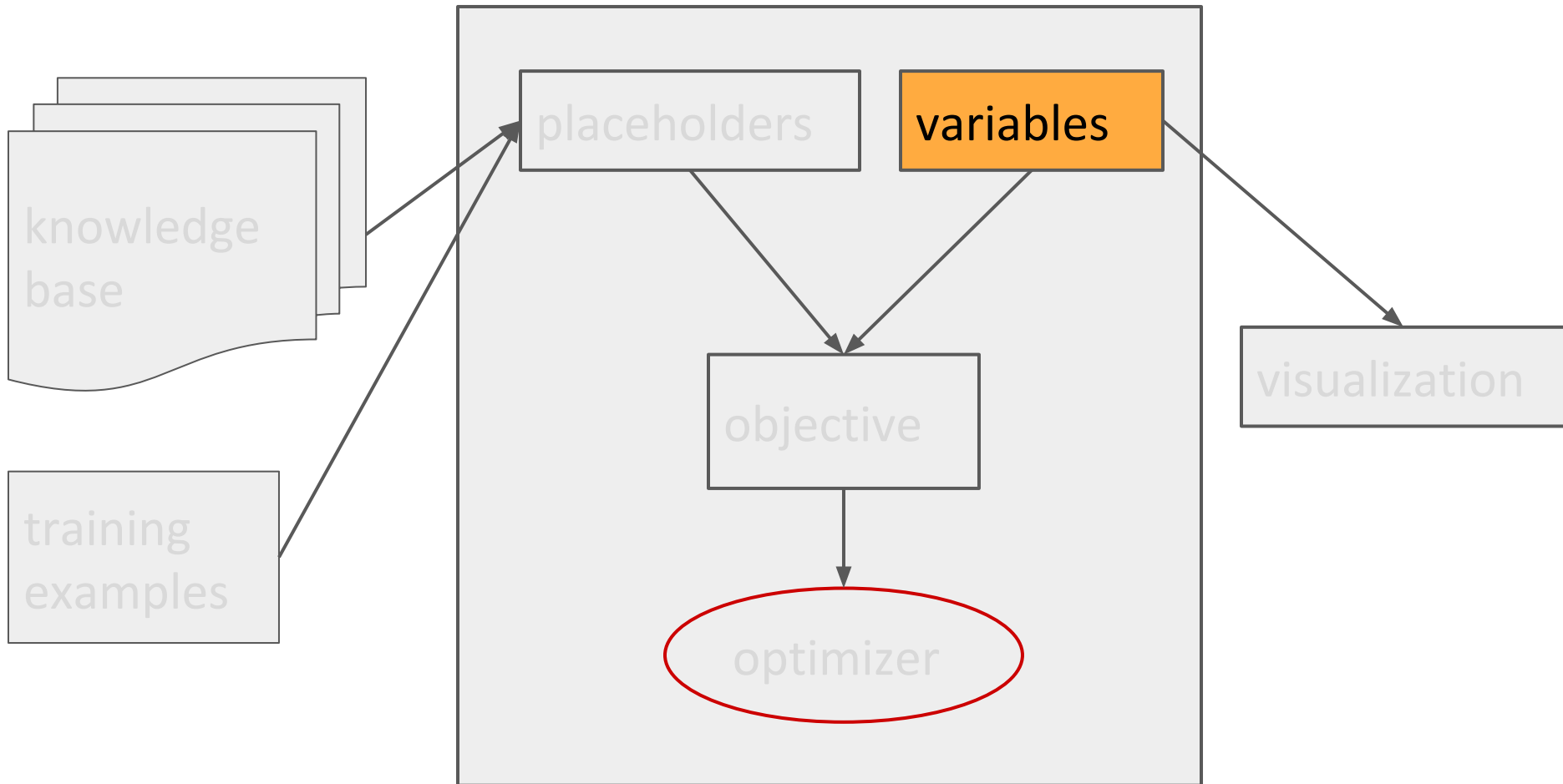
Implementation overview

TensorFlow graph

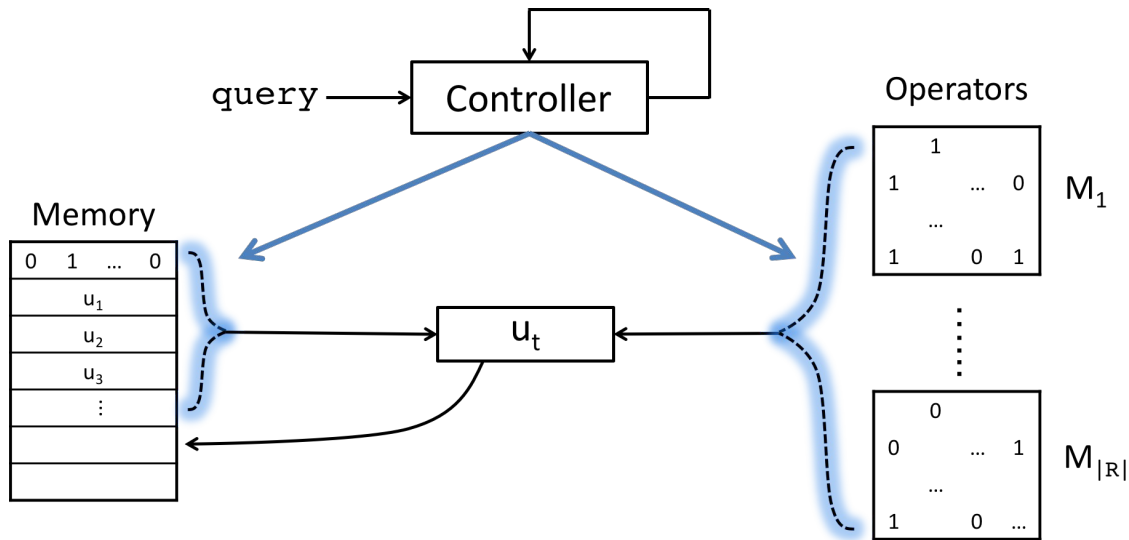


Learnable parameters

TensorFlow graph



Learnable parameters



Embeddings

RNN cell

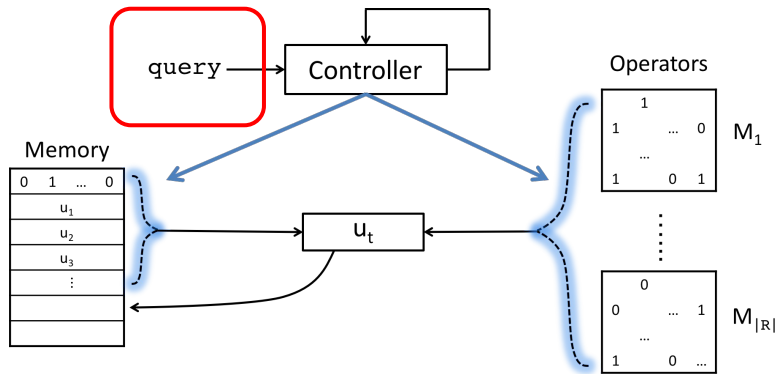
A linear layer

$$\mathbf{h}_t = \text{update}(\mathbf{h}_{t-1}, \text{input})$$

$$\mathbf{a}_t = \text{softmax}(W\mathbf{h}_t + b)$$

$$\mathbf{b}_t = \text{softmax}([\mathbf{h}_0, \dots, \mathbf{h}_{t-1}]^T \mathbf{h}_t)$$

Implementing the architecture 1/5



- Query format
 - Natural language
 - Structured

```
if not self.query_is_language:
    self.queries = tf.placeholder(tf.int32, [None, self.num_step])
    self.query_embedding_params = tf.Variable(self._random_uniform_unit(
        self.num_query + 1, # <END> token
        self.query_embed_size),
        dtype=tf.float32)

    rnn_inputs = tf.nn.embedding_lookup(self.query_embedding_params,
        self.queries)

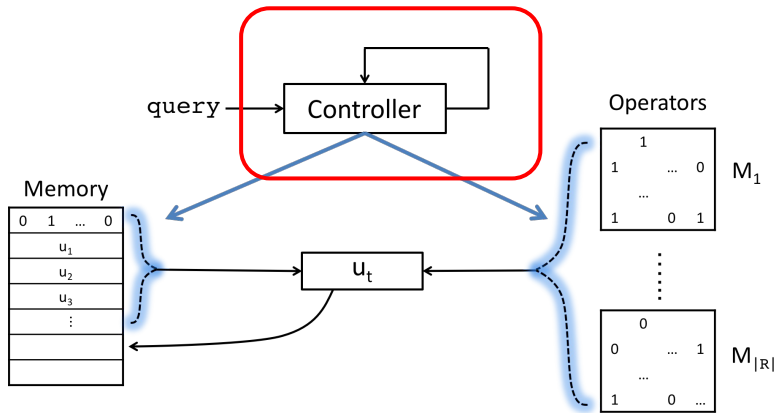
else:
    self.queries = tf.placeholder(tf.int32, [None, self.num_step, self.num_word])
    self.vocab_embedding_params = tf.Variable(self._random_uniform_unit(
        self.num_vocab + 1, # <END> token
        self.vocab_embed_size),
        dtype=tf.float32)

    embedded_query = tf.nn.embedding_lookup(self.vocab_embedding_params,
        self.queries)

    rnn_inputs = tf.reduce_mean(embedded_query, axis=2)

return rnn_inputs
```

Implementing the architecture 2/5



$$\mathbf{h}_t = \text{update}(\mathbf{h}_{t-1}, \text{input})$$

$$\mathbf{a}_t = \text{softmax}(W\mathbf{h}_t + b)$$

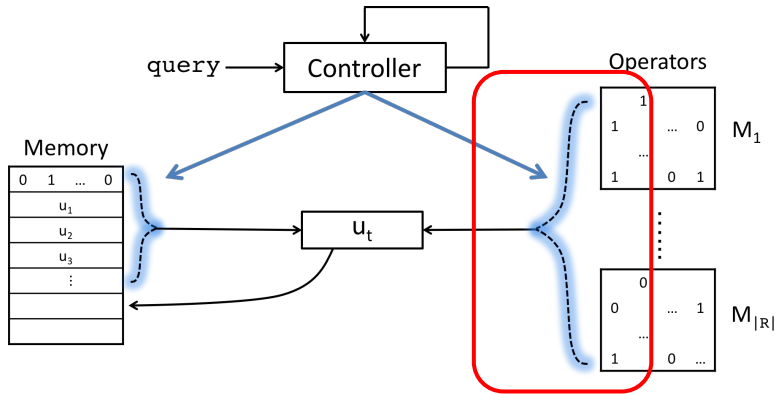
$$\mathbf{b}_t = \text{softmax}([\mathbf{h}_0, \dots, \mathbf{h}_{t-1}]^T \mathbf{h}_t)$$

```
""" Build a computation graph that represents the model """
rnn_inputs = self._build_input()
# rnn_inputs: a list of num_step tensors,
# each tensor of size (batch_size, query_embed_size).
self.rnn_inputs = [tf.reshape(q, [-1, self.query_embed_size])
                    for q in tf.split(rnn_inputs,
                                       self.num_step,
                                       axis=1)]

cell = tf.contrib.rnn.core_rnn_cell.LSTMCell(self.rnn_state_size,
                                             state_is_tuple=True)
self.cell = tf.contrib.rnn.core_rnn_cell.MultiRNNCell(
    [cell] * self.num_layer,
    state_is_tuple=True)
init_state = self.cell.zero_state(tf.shape(self.tails)[0], tf.float32)

# rnn_outputs: a list of num_step tensors,
# each tensor of size (batch_size, rnn_state_size).
self.rnn_outputs, self.final_state = tf.contrib.rnn.static_rnn(
    self.cell,
    self.rnn_inputs,
    initial_state=init_state)
```

Implementing the architecture 3/5



$$\mathbf{h}_t = \text{update}(\mathbf{h}_{t-1}, \text{input})$$

$$\mathbf{a}_t = \text{softmax}(W\mathbf{h}_t + b)$$

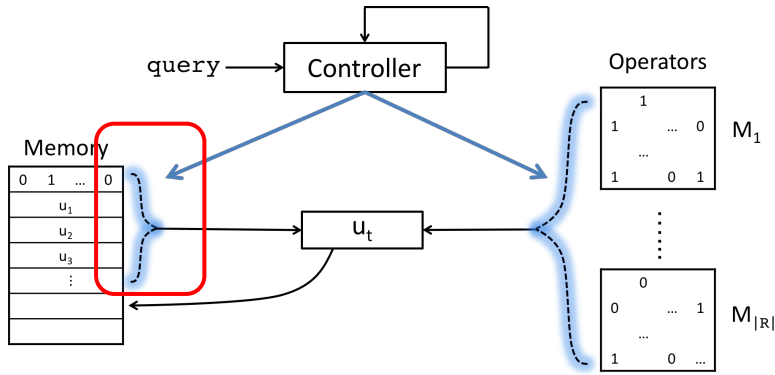
$$\mathbf{b}_t = \text{softmax}([\mathbf{h}_0, \dots, \mathbf{h}_{t-1}]^T \mathbf{h}_t)$$

```
self.W = tf.Variable(np.random.randn(
    self.rnn_state_size,
    self.num_operator),
    dtype=tf.float32)

self.b = tf.Variable(np.zeros(
    (1, self.num_operator)),
    dtype=tf.float32)

# attention_operators: a list of num_step lists,
# each inner list has num_operator tensors,
# each tensor of size (batch_size, 1).
# Each tensor represents the attention over an operator.
self.attention_operators = [tf.split(
    tf.nn.softmax(
        tf.matmul(rnn_output, self.W) + self.b),
    self.num_operator,
    axis=1)
    for rnn_output in self.rnn_outputs]
```

Implementing the architecture 4/5



$$\mathbf{h}_t = \text{update}(\mathbf{h}_{t-1}, \text{input})$$

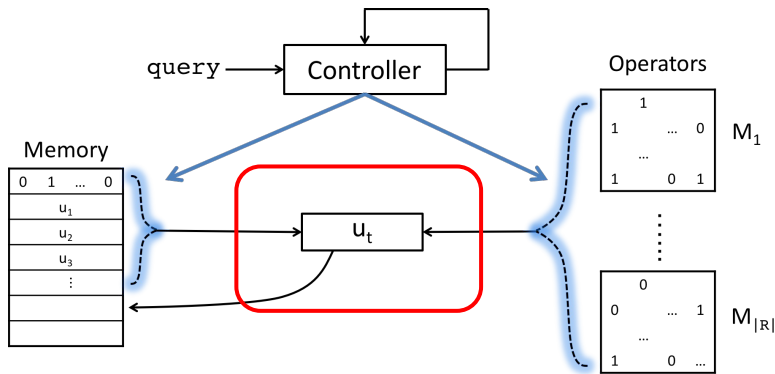
$$\mathbf{a}_t = \text{softmax}(W\mathbf{h}_t + b)$$

$$\mathbf{b}_t = \text{softmax}([\mathbf{h}_0, \dots, \mathbf{h}_{t-1}]^T \mathbf{h}_t)$$

```
for t in xrange(self.num_step):
    self.attention_memories.append(
        tf.nn.softmax(
            tf.squeeze(
                tf.matmul(
                    tf.expand_dims(self.rnn_outputs[t], 1),
                    tf.stack(self.rnn_outputs[0:t+1], axis=2)),
                squeeze_dims=[1])))

# memory_read: tensor of size (batch_size, num_entity)
memory_read = tf.squeeze(
    tf.matmul(
        tf.expand_dims(self.attention_memories[t], 1),
        self.memories),
    squeeze_dims=[1])
```

Implementing the architecture 5/5



```

for r in xrange(self.num_operator/2):
    for op_matrix, op_attn in zip(
        [self.database[r],
         tf.sparse_transpose(self.database[r])],
        [self.attention_operators[t][r],
         self.attention_operators[t][r+self.num_operator/2]]):
        product = tf.sparse_tensor_dense_matmul(op_matrix, memory_read)
        database_results.append(tf.transpose(product) * op_attn)

added_database_results = tf.add_n(database_results)

# Populate a new cell in memory by concatenating.
self.memories = tf.concat(
    [self.memories,
     tf.expand_dims(added_database_results, 1)],
    axis=1)
    
```

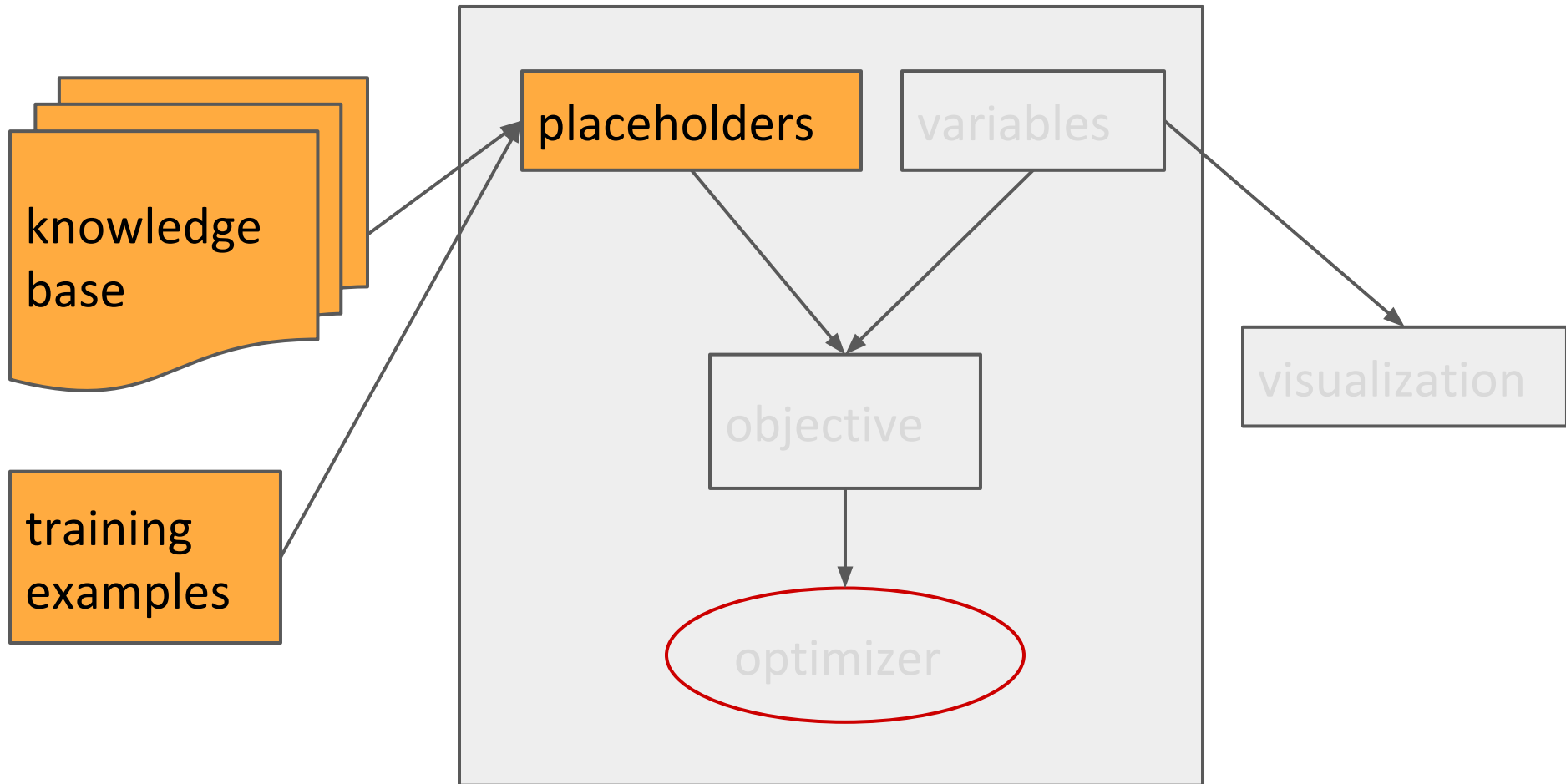
$$\mathbf{u}_0 = \mathbf{v}_x$$

$$\mathbf{u}_t = \sum_{\mathbf{k}} a_t^{\mathbf{k}} \mathbf{M}_{R_{\mathbf{k}}} \left(\sum_{\tau=0}^{t-1} b_t^{\tau} \mathbf{u}_{\tau} \right)$$

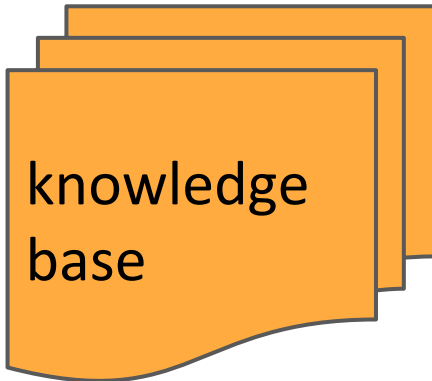
$$\mathbf{u}_{T+1} = \sum_{\tau=0}^T b_{T+1}^{\tau} \mathbf{u}_{\tau}$$

Data flow

TensorFlow graph



Data representation

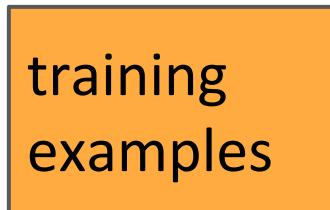


Format:

- e_A Relation e_B

num_operator

num_entity



Format:

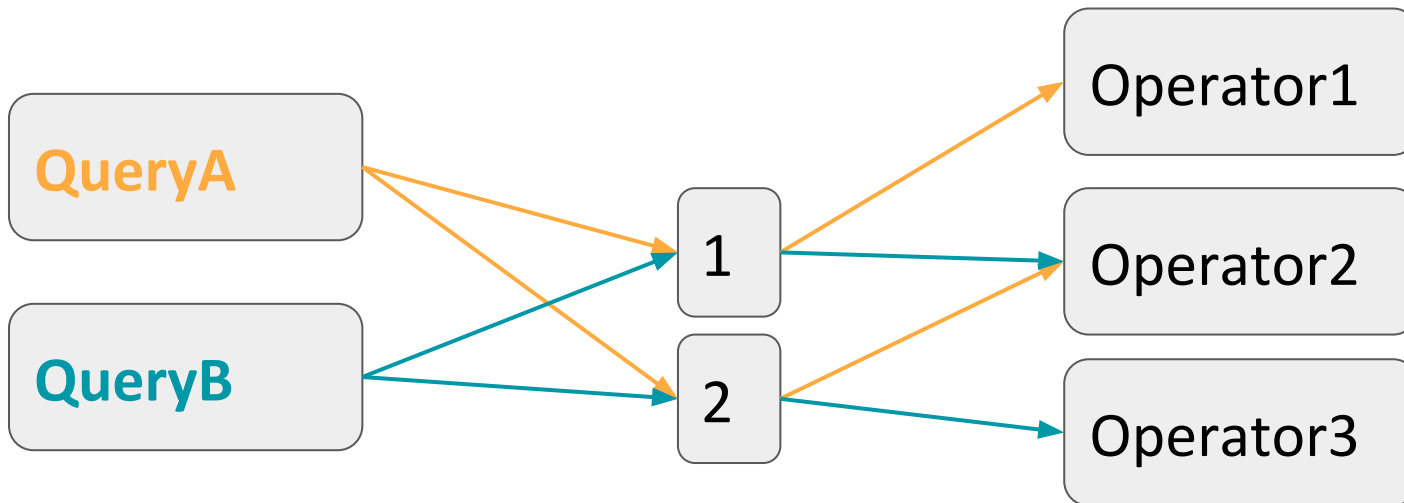
- natural language
 - $e_{\text{head}}, w_1, \dots, w_n, e_{\text{tail}}$
- structured
 - $e_{\text{head}}, \text{query}, e_{\text{tail}}$

num_vocab

num_query

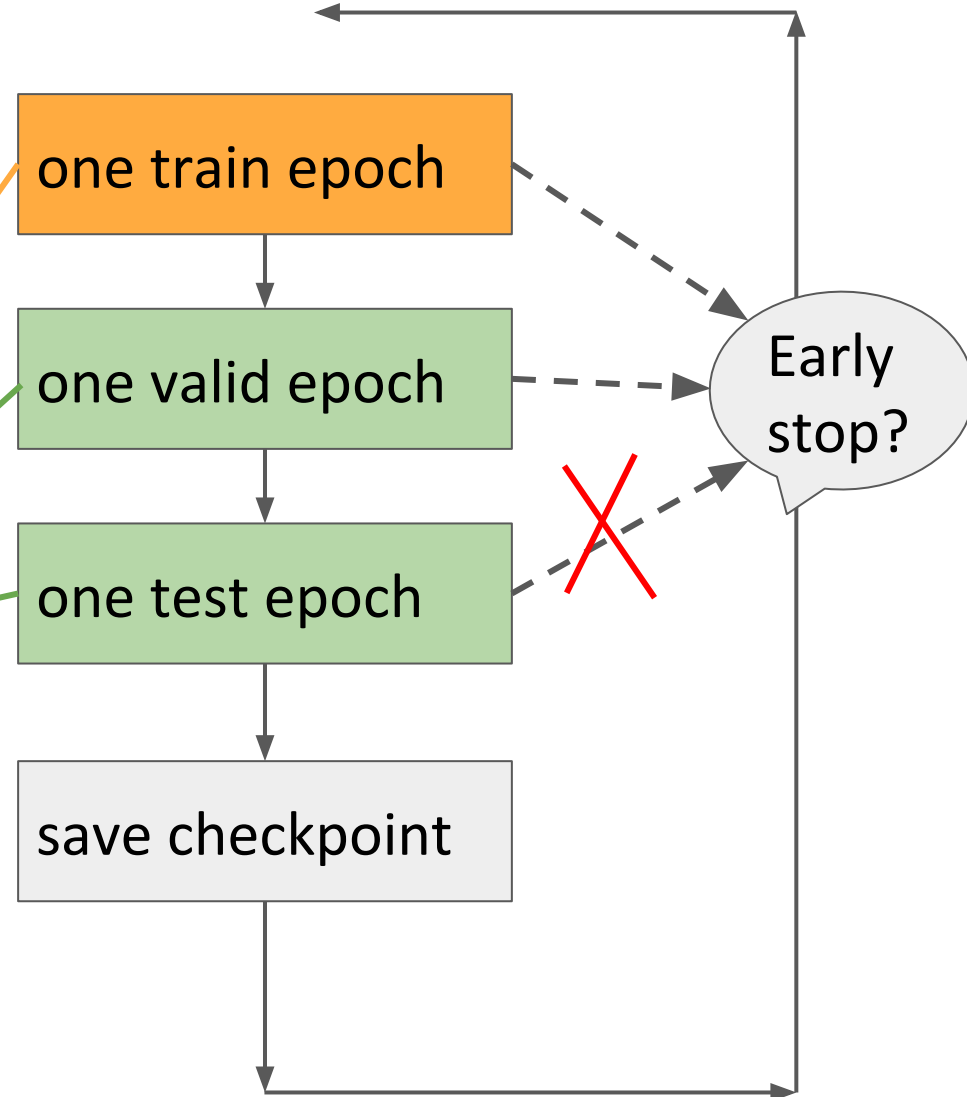
Data representation

- Mapping
 - query_to_id
 - Used to look up embeddings.
 - id_to_operator
 - Can vary across queries.



Training

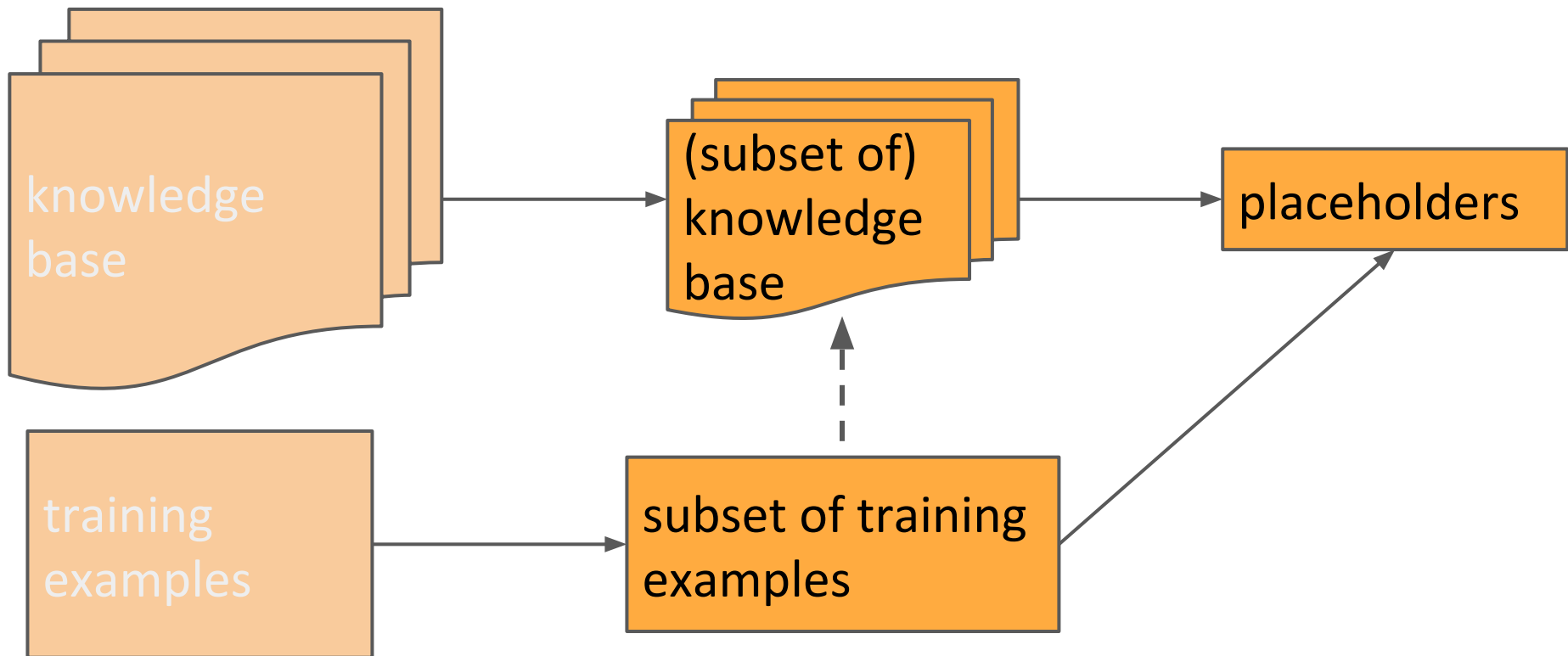
```
def one_epoch(self, mode, num_batch, next_fn):  
    epoch_loss = []  
    epoch_in_top = []  
    for batch in xrange(num_batch):  
        if (batch+1) % max(1, (num_batch / self.option.pr  
            sys.stdout.write("%d/%d\t" % (batch+1, num_b  
            sys.stdout.flush()  
  
        (qq, hh, tt), mdb = next_fn()  
        if mode == "train":  
            run_fn = self.learner.update  
        else:  
            run_fn = self.learner.predict  
        loss, in_top = run_fn(self.sess,  
                               qq,  
                               hh,  
                               tt,  
                               mdb)  
  
        epoch_loss += list(loss)  
        epoch_in_top += list(in_top)
```



Training

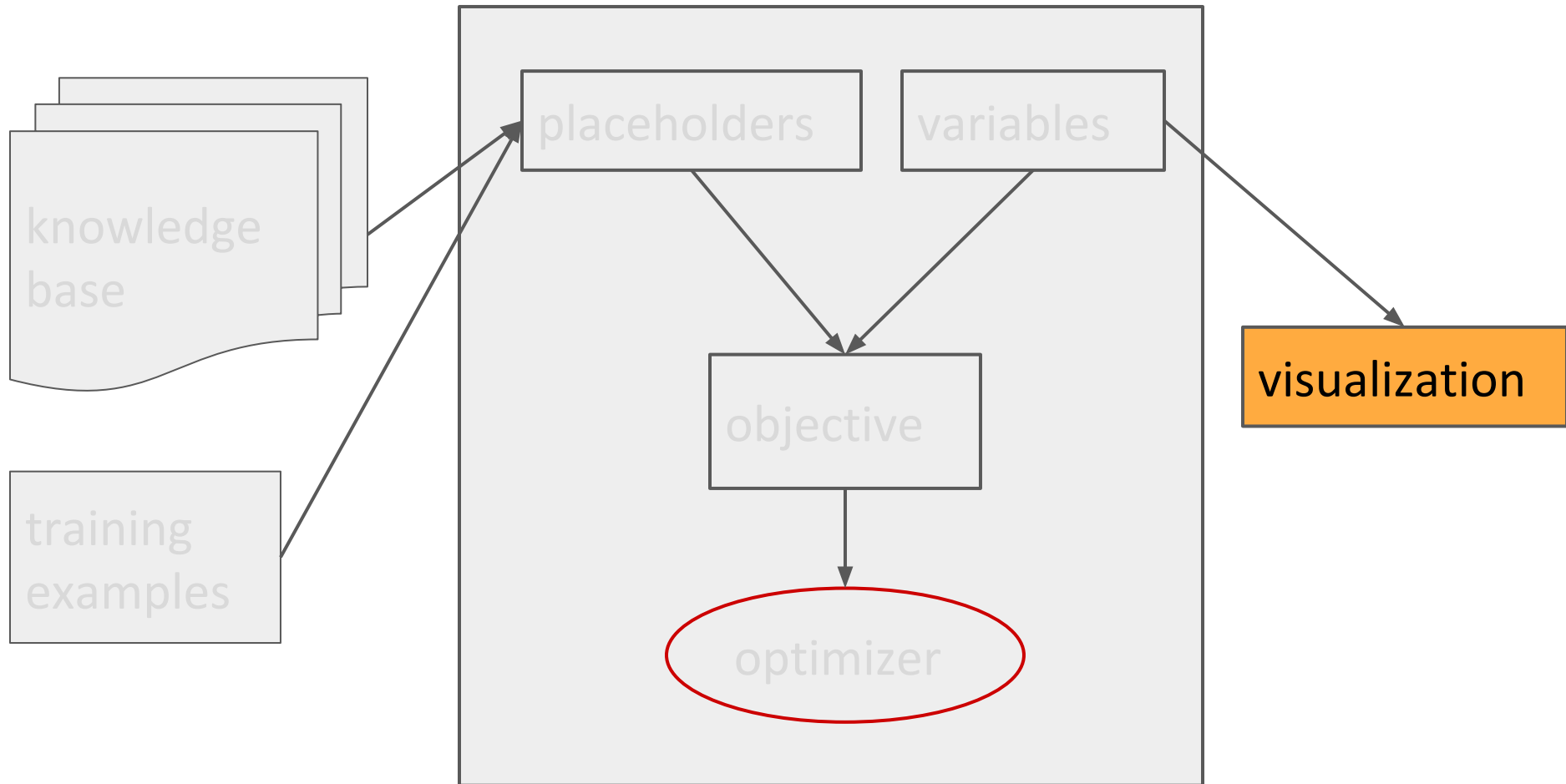
- **Batching**

- Batch size depends on how much CPU/GPU memory is available.
- Examples in the batch use the same knowledge base.



Sidelines

TensorFlow graph



Future work

- Scalability
 - Use graph sampling to reduce num_entity.
- Expressiveness
 - Extend chain-like rules to poly-tree.
- Application
 - Queries in the format of images.

Thanks!

Checkout our implementation at:

<https://github.com/fanyangxyz/Neural-LP>